New Collisions to Improve Pollard's Rho Method of Solving the Discrete Logarithm Problem on Elliptic Curves

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Abstract: It is true that different approaches have been utilised to accelerate the computation of discrete logarithm problem on elliptic curves with Pollard's Rho method. However, trapping in cycles fruitless will be obtained by using the random walks with Pollard's Rho. An efficient alternative approach that is based on new collisions which are reliant on the values a_i , b_i to solve this problem is proposed. This may requires less iterations than Pollard's Rho original in reaching collision. Thus, the performance of Pollard's Rho method is more efficiently because the improved method not only reduces the number of mathematical operations but these collisions can also applied on previous improvements which reported in the literature.

Keywords: Pollard's Rho, Elliptic Curve Discrete Logarithm, Alternative Collisions

Introduction

The technology of public key cryptography has been proposed by (Diffie and Hellman, 1976) whereas the elliptic curve cryptosystems (ECC_s) that is dependent on this technology were first proposed separately by (Miller, 1986; Koblitz, 1987). The security of these cryptographic systems is reliant on the hardness of solving the discrete logarithm problem on elliptic curves (ECDLP). These schemes will be broken easily if this problem can be resolved efficiently. Despite the fact that there are several attacking methods to resolve ECDLP, Pollard's Rho method (Pollard, 1980) not only is at present known as the fastest algorithm to resolve the discrete logarithm problem on elliptic curves, but its parallelized variant as well because its mathematical operations is less than other methods like Baby-Step Giant-Step (Shanks, 1971). This encourages researchers to utilise from automorphism of the group (Duursma et al., 1990), random walk on certain equivalence classes (Wiener and Zuccherato, 1999; Gallant et al., 2000), parallelization (Oorschot and Wiener, 1999), iteration function (Teske, 1998; 2001), negation map (Wang and Zhang, 2012) or cycle detection (Brent, 1980; Cheon et al., 2012; Ezzouak et al., 2014) to improve this attacking method. This paper will provide a new approach by using the theorem that proposed by (Sadkhan and Neamah, 2011) to improve Pollard's Rho method which use alternative collisions to resolve the ECDLP.

After that, the developed method will be analysed by giving examples.

Background

In this section, the mathematical background of elliptic curve cryptography and the Pollard Rho method (Pollard, 1980) that uses an iteration function to make a succession of elements will be presented. This technique utilises cycle detection to find collision or a match. This matching will contribute to the solution of ECDLP.

Elliptic Curve Cryptography (ECC)

Elliptic Curves over the prime field F_p can be defined by the equation $y^2 = x^3 + ax + b$, where $4a^3 + 27b^2 \neq 0$. Different curves can be generated by changing the values *a* and *b* which belongs to F_p . The set of points (x, y) that satisfy this equation equipped with the addition operation forms a group, denoted by $E(F_p)$. This operation can be defined over elliptic curves with a particular point O_{∞} which is called the identity or the point at infinity. If $P = (x_1, y_1)$ and $Q = (x_2, y_2)$ belongs to $E(F_p)$, $P \oplus Q = R = (x_3, y_3)$ can be added as follows:

- If $P = O_{\infty}$, $Q = O_{\infty}$ or $P = O_{\infty}$ and $Q = O_{\infty}$ then R respectively equal Q, P or O_{∞}
- If $Q = \Theta P = (x_1, y_1)$ and $P \oplus (\Theta P) = O_{\infty}$
- Otherwise $P \oplus Q = (x_3, y_3)$ where:

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and:

$$\lambda = \begin{cases} \frac{3x_1^2 + a}{2y_1} & \text{if } P = Q\\ \frac{y_2 - y_1}{x_2 - x_1} & \text{if } P \neq Q \end{cases}$$

 $x_3 = l^2 - x_1 - x_2, y_3 = l \times (x_1 - x_3) - y_1$

In ECC_s, obtaining the public key is made out multiplying the private key that is a random number k, belongs to the interval [1, n-1] with a point P which has order n. The point P is called the generator of a cyclic group $\langle P \rangle = \{O_{\alpha}, P, [2]P, ..., [n-1]P\}$ and its order can be defined as the smallest positive scalar n such that $[n]P = O_{\alpha}$ which symbolized by ord (P). The strength of the ECC_s security is reliant on the ECDLP. This problem can be defined as follows: Let P has order n, which belongs to the points of an elliptic curve defined over the field F_p and a point $Q \in \langle P \rangle$, then finding $k \in [1, n-1]$ such that $Q = [k]P = \underbrace{P \oplus P \oplus \cdots \oplus P}_{k \text{ tumes}}$ is called the

discrete log of Q to the base P which is symbolized by $k = log_P Q$. Because k can be inferred from Q if the ECDLP is easy, so the difficulty of the ECDLP plays a crucial role in the security of these cryptographic systems (Hankerson *et al.*, 2004; Chee and Park, 2005).

Theorem

Let Q a point belongs to group points that generated by P where ord (P) = n and R can be calculated as follows: $[a]P \oplus [b]Q$ where $a, b \in [1, n-1]$ then the following equations can be obtained (Sadkhan and Neamah, 2011):

- 1. If $R = O_{\alpha}$ and gcd (b, n) = 1 then $\log_p Q = \frac{n-a}{b} \mod n$
- 2. If R = P and gcd (b, n) = 1 then $\log_p Q = \frac{1-a}{b} \mod n$
- 3. If R = Q and gcd (1 b, n) = 1 then $\log_p Q = \frac{a}{1 b} \mod n$
- 4. If $R = \bigoplus P$ and gcd (b, n) = 1 then $\log_p Q = \frac{-1-a}{b} \mod n$
- 5. If $R = \bigoplus Q$ and gcd (-1-b, n) = 1 then $\log_p Q = \frac{a}{-1-b} \mod n$

Pollard's Rho Method

The Pollard idea is to find k which is satisfying Q = [k]P by dividing the group of points on an elliptic curve into three disjoint sets S_1 , S_2 and S_3 which have an almost equal size. Define the original iteration function on a point R as follows:

$$f(R) = \begin{cases} R \oplus P, & \text{if } R \in S_1 \\ [2]R & \text{if } R \in S_2 \\ R \oplus Q, & \text{if } R \in S_3 \end{cases}$$
(1)

Start with a point $R_0 = [a_0]P \oplus [b_0]Q$ where $a_0, b_0 \in [1, n-1]$ are randomly chosen and make a sequence R_i by using this function until the collision occurs. The sequence R_i can be expressed as $[a_i]P \oplus [b_i]Q$, where the numbers $a_i, b_i \in [1, n-1]$ are calculated as following:

$$a_{i+1} = \begin{cases} (a_i + 1)mod n & if R_i \in S_1 \\ 2a_i \mod n & if R_i \in S_2 \\ a_i & if R_i \in S_3 \end{cases}$$

and
$$b_{i+1} = \begin{cases} b_i & if R_i \in S_1 \\ 2b_i \mod n & if R_i \in S_2 \\ (b_i + 1)mod n & if R_i \in S_3 \end{cases}$$

Since the number of points that lies in the curve that form cyclic group is a finite, this sequence will not only become periodic after applying this function but will start to repeat. Upon detection of a matching, this is R_i = $R_j \Rightarrow [a_i]P \oplus [b_i]Q = [a_j]P \oplus [b_j]Q$, if gcd $(b_j-b_i, n) =$ 1, *k* can be obtained as follows (Wiener and Zuccherato, 1999).

$$k = \log_P Q = \left(\frac{a_i - a_j}{b_j - b_i}\right) \mod n$$

Example 1

Let $y^2 = x^3 + 130 x + 565$ an elliptic curve is defined over F_{719} and let P = (312, 90) point has order 233 on elliptic curve points. The discrete logarithm of point Q =(475, 662) to the base P can be computed as follows:

The points of this curve are $\{O_{\alpha}, (0, 224), \dots, (718, 282), (718, 437)\}$, the partitions of these points as follows:

 $S_1 = \{O_{\alpha}, (0, 224), (0, 495), \dots, (238, 302), (238, 417)\}$ $S_2 = \{(241, 293), (241, 426), \dots, (475, 57), (475, 662)\}$ $S_3 = \{(481, 169), (481, 550), \dots, (718, 282), (718, 437)\}$

Let $a_0, b_0 \in [1, n-1]$ are selected as follows: $a_0 = 2, b_0 = 87$ then R_0 can computed as follows: $[a_0]P \oplus [b_0]Q = [2](312, 90) \oplus [87](475, 662) = (312, 90).$

Which gives:

$$k = \frac{a_4 - a_{18}}{b_{18} - b_4} \mod 233 = \frac{10 - 84}{31 - 117} \mod 233 = (159).147^{-1} \mod 233 = 158$$
 Thus $k = \log_p Q = 158$

Example 2

Let $y^2 = x^3 + 250 x + 844$ an elliptic curve is defined over F_{1009} and let P = (909, 601) point has order 1007 on elliptic curve points. The discrete logarithm of point Q =(134, 52) to the base P can be computed as follows:

The points of this curve are $\{O_{\alpha}, (2, 315), \dots, (1007, 423), (1007, 586)\}$, the partitions of these points as follows:

 $S_1 = \{O_{\infty}, (2, 315), (2, 694), \dots, (335, 138), (335, 871)\}$ $S_2 = \{(338, 328), (338, 681), \dots, (688, 407), (688, 602)\}$ $S_3 = \{(691, 67), (691, 942), \dots, (1007, 423), (1007, 586)\}$

Let $a_0, b_0 \in [1, n-1]$ are chosen as follows: $a_0 = 45$, $b_0 = 229$ then R_0 can calculated as follows: $[a_0]P \oplus [b_0]Q = [46](909, 601) \oplus [229](134, 52) = (981, 997)$. Which gives:

$$k = \frac{a_{22} - a_{48}}{b_{48} - b_{22}} \mod 1007 = \frac{838 - 129}{736 - 108} \mod 1007$$
$$= (709).628^{-1}1007 = 766 \ Thus \ k = \log_P Q = 766$$

Improving Pollard's Rho Method by Using New Equations

The main idea of alternative collision of pollard's Rho on elliptic curve group method is that looks for a new collision in the group. Using the equations has been proposed by (Sadkhan and Neamah, 2011) in Theorem above can not only significantly contribute to improving this method by reducing the mathematical operations but collision-detection algorithms can also be applied. Elliptic curve points over field F_p divide into three disjoint sets S_1 , S_2 and S_3 with iterative function defined as follows:

$$f(R) = \begin{cases} R \oplus P, & \text{if } R \in S_1 \\ [2]R & \text{if } R \in S_2 \\ R \oplus Q, & \text{if } R \in S_3 \end{cases}$$
(2)

The sequence R_i can be expressed as $[a_i]P \oplus [b_i]Q$, where the numbers $a_i, b_i \in [1, n-1]$ are calculated as following:

$$a_{i+1} = \begin{cases} (a_i + 1)mod \ n & if \ R_i \in S_1 \\ 2a_i \mod n & if \ R_i \in S_2 \\ a_i & if \ R_i \in S_3 \end{cases}$$

and
$$b_{i+1} = \begin{cases} b_i & if \ R_i \in S_1 \\ 2b_i \mod n & if \ R_i \in S_2 \\ (b_i + 1)mod \ n & if \ R_i \in S_3 \end{cases}$$

The collision-detection will occur with the following equations after applying the iteration function:

- 1. If $R_i = O_{\infty}$ and $\gcd(b_i, n) = 1$ then $k = \log_p Q = \frac{n - a_i}{b_i} \mod n$
- 2. If $R_i = P$ and gcd $(b_i, n) = 1$ then $k = \log_P Q = \frac{1 - a_i}{b_i} \mod n$
- 3. If $R_i = Q$ and gcd $(1-b_i, n) = 1$ then $k = \log_p Q = \frac{a_i}{1-b_i} \mod n$
- 4. If $R_i = \bigoplus P$ and gcd $(b_i, n) = 1$ then $k = \log_P Q = \frac{-1 - a_i}{b_i} \mod n$
- 5. If $R_i = \bigoplus_{i=1}^{n} Q$ and gcd $(-1-b_i, n) =$ $1 k = \log_p Q = \frac{a_i}{-1-b_i} \mod n$

If such collisions cannot be obtained, the original collision $R_i = R_j$, or the reverse collision $R_i = \bigcirc R_j$ respectively can be applied as follows:

I. Log_P Q can be obtained as follows: $k = \left(\frac{a_i - a_j}{b_j - b_i}\right)$ mod n if scd $(b_j - b_i) = 1$

II.
$$\text{Log}_P Q$$
 can be obtained as follows:
 $k = \left(\frac{a_i + a_j}{-b_i - b_j}\right) \mod n, \text{ if gcd } (-b_i - b_j, n) = 1$

Example 3

From example (1) since $R_i = R_0 = P$ and gcd (87, 233) = 1 then condition (2) can be applied $k = \log_P Q = \frac{1-a_0}{b_0} \mod n = \frac{232}{87} \mod 233 = (232).87^{-1}$ mod 233 = 158. Thus $k = \log_P Q = 158$. Or, Since $R_i = R_{12} = \bigoplus P$ and gcd (13, 233) = 1 then the condition (4) can also be applied $k = \log_P Q = \frac{-1-a_{12}}{b_{12}} \mod n = \frac{190}{13} \mod 233 = (190).13^{-1} \mod 233 = 158$. Thus $k = \log_P Q = 158$.

Example 4

From example (2) since $R_8 = \bigoplus R_{38}$ and gcd (419, 1007) = 1 then the condition (ii) can be applied $k = \frac{a_8 + a_{38}}{-b_8 - b_{38}} \mod n = \frac{373 + 355}{-842 - 753} \mod 1007 = (728).419^{-1}$ mod 1007 = 766. Thus $k = \log_P Q = 766$. Or. Since $R_i = R_1 = P$ and gcd (230, 1007) = 1 then the condition (2) can also be applied $k = \log_P Q = \frac{1 - a_1}{b_1} \mod \frac{1 - a_2}{b_1}$

 $1007 = \frac{962}{230} \mod 1007 = (962).230^{-1} \mod 1007 = 766.$ Thus $k = \log_{\mathbb{D}} Q = 766.$

Comparison between Methods

Analysing the methods play a crucial role in computer programming, so knowing the best methods is depended on this analysis because there are many methods available to a specific application. The performance of these methods such as Pollard's Rho can be evaluated by computing mathematical operations. If such methods have fewer steps than others, running time will be the best. Therefore, the developed Pollard's Rho method that implemented in these examples have shown the mathematical operations can be reduced from 18 to 1 or 12 operations with respect to the first example and from 48 to 2 operations or 38 in the worst case by using the reverse collision $R_i = \Theta R_i$ with respect to the second example. These examples have utilised prime numbers with size between three and four digits. The Table 1 and 2 of these examples show that the intermediate steps of Pollard's Rho method. The experimental results for this method with its new equations have been certainly improved because the point Q belong to a cyclic group which generated by *P* will always contain the points *P*, $Q, \ominus P, \ominus Q$ and O_{∞} in this group. This implies these collisions not only have always occurred but the probability of a collision has also significantly increased if it compared with original method.

Table 1. Shows the intermediate steps of Pollard's Rho method

i	R_i	a_i	b_i
0	(312, 90) = P	2	87
1	(567, 38)	4	174
2	(56, 560)	4	175
3	(366, 290)	5	175
4	(665, 336)	10	117
5	(508, 598)	10	118
6	(400, 173)	10	119
7	(63, 276)	20	5
8	(422, 356)	21	5
9	(548, 457)	42	10
10	(676, 651)	42	11
11	(671, 150)	42	12
12	$(312, 629) = \ominus P$	42	13
13	(567, 681)	84	26
14	(670, 259)	84	27
15	(636, 198)	84	28
16	(627, 111)	84	29
17	(630, 529)	84	30
18	(665, 336)	84	31

Since $R_4 = R_{18} = (665, 336)$, then $[a_4]P \oplus [b_4]Q = [a_{18}]P \oplus [b_{18}]Q$

 $[10](312, 90) \oplus [117](475, 662) = [84](312, 90) \oplus [31](475, 90)$

It can be concluded that the proposed improved method will be better than the original pollard's Rho method and these alternative collisions can also be applied to previo

us proposed improvements such that dividing the group into about 20 sets (Teske, 1998; 2001).

Table 2. Shows the intermediate steps of Pollard's Rho method

	e intermediate steps	of Pollard's Rho r	
i	R_i	a_i	b_i
0	(981, 997)	46	229
1	(909, 601) = P	46	230
2	(376, 671)	46	231
3	(113, 377)	92	462
4	(387, 58)	93	462
5	(482, 151)	186	924
6	(990, 873)	372	841
7	(30, 821)	372	842
8	(449, 876)	373	842
9	(434, 695)	746	677
10	(585, 82)	485	347
11	(974, 474)	970	694
12	(621, 167)	970	695
13	(502, 420)	933	383
14	(841, 440)	859	766
15	(160, 95)	859	767
16	(696, 855)	860	767
17	(368, 23)	860	768
18	(890, 335)	713	529
19	(657, 202)	713	530
20	(776, 151)	419	53
21	(445, 612)	419	54
22	(164, 541)	838	108
23	(993, 794)	839	108
24	(382, 677)	839	109
25	(454, 843)	671	218
26	(128, 749)	335	436
27	(819, 254)	336	436
28	(168, 891)	336	437
29	(932, 481)	337	437
30	(818, 301)	337	438
31	(270, 996)	337	439
32	(809, 842)	338	439
33	(206, 940)	338	440
34	(15, 152)	339	440
35	(597, 348)	340	440
36	-141,004	680	880
37	(595, 332)	681	880
38	(449, 133)	355	753
39	(434, 314)	710	499
40	(585, 927)	413	998
41	(974, 535)	826	989
42	(607, 458)	826	990
43	(660, 171)	645	973
44	(72, 278)	283	939
45	(351, 287)	284	939
46	(662, 783)	568	871
47	(697, 56)	129	725
48	(164, 541)	129	736
Since $R_{22} = R_{48} =$	(164, 541), then [$a_{22}]P \oplus [b_{22}]Q =$	$[a_{48}]P$

Since $R_{22} = R_{48} = (164, 541)$, then $[a_{22}]P \oplus [b_{22}]Q = [a_{48}]P \oplus [b_{48}]Q$ [838](909, 601) \oplus [108](134, 52) = [129](909, 601) \oplus

[736](134, 52)

Conclusion

The improved Pollard's Rho method has been outlined by using new collisions. These collisions are reliant on values a_0 and b_0 that have been playing a significant role in reducing the total number of mathematical operations if these values are chosen carefully. This means selecting these numbers will significantly contribute to solve the ECDLP quickly. This modified method can be considered as an important addition to methods of improving the Pollard's Rho. Although these results are related to small prime finite fields, this can represent a good reduction of complexity when it is applied by using large prime numbers. The parallel collision search can also be applied by selecting different start points which have different values a_0 and b_0 for each processor in order to produce their own sequences of points, so the chance of collision will be considerably increased. This means the collision may not only occur with the points $P, Q, \Theta P$, $\bigcirc Q$ and O_{∞} more than once but also with the points R_i and ΘR_i in the worst case.

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Ethics

This article is original and contains unpublished materials. The corresponding author confirms that all of the other authors have read and approved the manuscript and no ethical issues involved.

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